Simela smart electric actuators

liteECO[®] Linear Actuators

LINEAR TELESCOPABLE ELECTROMECHANICAL CONCEPT

The most compact electromechanical alternative to pneumatic cylinders

Characteristics

High force and dynamic Integrated encoder system Integrated anti-rotation mechanism (option) High utilization of the installation length for the stroke Configurable motion profiles with differnet motion controllers Plug & play replacement for pneumatic cylinders (based on ISO 15552) Combined connection for power and sensor signals (single cable solution)

Advantageous Pneumatic Replacement

The liteECO® linear actuators are ideal for applications that require short linear movements: e.g. in production lines, machine tools, or packaging systems. For simple and complex movements: for fixing, adjusting, locking or following any motion profile.

In the process, they save more than 75 % energy compared to pneumatic systems and up to 80 % installation space compared to existing electrical solutions.

The dynamic positioning capability as well as simple and fast integration into the Industry 4.0 world represent significant advantages.

Awards



Product Configuration



SMELA GmbH Liebknechtstraße 55 - 39108 Magdeburg

www.smela.com info@smela.com Document: DS-LE48-EN Version: 004 - Date: 04.04.2022

smart electric actuators

Technical Data

Dimensions, Coupling, Materials				
48 x 48 mm				
84 mm				
11 mm (LE48.A LE48.C) 10 mm (LE48.D)				
approx. 440 g				
< 5 Nm				
< 1 Nm				
4 x M5 (internal thread) 8 20 mm				
M6 (external thread)				
DA26 (HD 26M D-SUB plug)				
IP 40				
stainless steel (1.4305) aluminum (AW6082) FDA conform polymer HPU (hydrolysis-resistant polyurethane)				

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Somela smart electric actuators

Technical Data

Performance data	Unit	LE48.A*	LE48.B*	LE48.C	LE48.D
Max. stroke Anti-rotation ¹⁾ No anti-rotation ²⁾	mm mm		50 56		- 46 ³⁾
Max. force (static) ⁴⁾	Ν	125	200	300	800
Nominal force (quasi-static) ⁵⁾ Poor thermal coupling ⁶⁾ Good thermal coupling ⁷⁾	Ν	41 62,5	66 100	100 150	500 500
Max. speed ⁸⁾	mm/s	1.200	750	500	90
Max. acceleration ⁹⁾	m/s ²	60	37,5	25	2
Positioning time ¹¹⁾	ms	approx. 65	approx. 90	approx. 125	approx. 600
Backlash ¹¹⁾	mm	± 0,1 ± 0,05			
Nominal voltage	V	24 bis 48			
Max. phase current ¹²⁾	А	12 6			6
Nom. phase current (quasi-static) ¹³⁾ Poor thermal coupling ⁶⁾ Good thermal coupling ⁷⁾	A A	2,9 5,0			
Operating temperature ¹⁴⁾	°C	+5 to +40			
Internal temperature limit	°C	+90			
Position sensor system	-	incremental, hall, SSI*, limit position sensor*			

Explanatory footnotes:

* planned variant / on request

- 1) With integrated anti-rotation mechanism of the plunger
- 2) Without integrated anti-rotation mechanism of the plunger
- 3) Currently only configurable without integrated anti-rotation mechanism of the plunger and a max. stroke of 46 mm
- 4) Max. static force and axial load capacity of the plunger as well as the internal mechanics;
- exceeding loads are not permissible and must be absorbed by external mechanics or brakes
- 5) The quasi-static nominal force was determined by continuous positioning under nominal load;
- Positioning process: upstroke: 800 ms, holding time: 200 ms, downstroke: 800 ms, holding time: 200 ms, 100% duty cycle 6) With thermal insulation (actuator in air)
- 7) When connected to an aluminum mounting plate with a convection surface of approx. 200 cm²
- 8) The applied voltage (conductor-conductor) can be up to 48 V. The characteristic data refer to a nominal voltage of 24V (at the actuator);
- the actual voltage at the actuator can deviate from the DC link voltage and depends on the used frequency inverter and the length of the cable 9) During braking (negative acceleration), energy is generated and fed back into the DC link; if the DC link is not capable of regenerative braking,
- care must be taken to ensure adequate dimensioning of the DC link capacity and/or the use of an additional brake chopper 10) Over the entire stroke with an operating voltage of min. 24 V; without load
- 11) The backlash is dependent on wear; the wear is dependent on load, dynamics and mileage
- 12) The max. phase current can be applied for max. 20 seconds in order not to exceed the internal limit temperature of 90 °C, starting from an initial temperature of the actuator of 20°C
- 13) Permissible rated phase current not to exceed the winding temperature of 90°C at an ambient temperature of 20 °C
- 14) Max. permissible ambient temperature; the internal temperature limit (90 °C) is not allowed to exceed

SMELA GmbH reserves the right to make changes in the sense of technical improvements and new findings.

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Pin Assignment



liteECO [®] Actuator connection DA26 (HD 26M D-SUB plug)				
PIN No.	Function	Note		
1	GND	DC power supply for sensors		
2	Enc A	with sensor configuration Sx0, Sx1		
3	Enc B	with sensor configuration Sx0, Sx1		
4	Enc Z	with sensor configuration Sx0, Sx1		
5	Temp +	optional, on request		
6	Switch pos. limit	optional with sensor configuration S1x		
7	Hall Sensor 1	with sensor configuration Sx1		
8	Hall Sensor 2	with sensor configuration Sx1		
9	-	-		
10	Motor Phase 1	-		
11	5 V	DC power supply for sensors		
12	Enc !A	with sensor configuration Sx0, Sx1		
13	Enc !B	with sensor configuration Sx0, Sx1		
14	Enc !Z	with sensor configuration Sx0, Sx1		
15	Temp -	optional, on request		
16	Switch neg. limit	optional with sensor configuration S1x		
17	Hall Sensor 3	with sensor configuration Sx1		
18	GND	DC power supply for sensors		
19	Motor Phase 1	-		
20	Motor Phase 1	-		
21	Motor Phase 2	-		
22	Motor Phase 2	-		
23	Motor Phase 2	-		
24	Motor Phase 3	-		
25	Motor Phase 3	-		
26	Motor Phase 3	-		

Note: Pre-assembled cables suitable for drag chains are available on request via sales@smela.com.



DA26 (HD 26M D-SUB plug)

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